

FEEG6013 Group Design Project

# GDP 28: Access Gate for Disabled Ramblers

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**Supervisor:**

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**Co-Supervisor:**

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# Group Members and Roles

**Mark Newman:**

Team Leader

**Aaron Horsfield:**

Vice Team Leader & Electronics Lead

**Jessica Shum:**

Ethics and Research Lead

**James Maybey:**

CAD and Design Lead

**Ming Sheng:**

Secretary and Treasurer



# The Brief

Design a structure that **allows mobility scooters** through but **excludes motorcycles**



disabled  
ramblers

# Aim and Objectives

**Aim:** Design and manufacture a prototype structure that is both motorcycle-detererring and more accessible for mobility scooter users than current designs on the market

## **Objectives:**

1. Investigate existing designs and viewpoints of relevant stakeholders
2. Form a product design specification and identify areas for improvement
3. Produce multiple design solutions that resolve the design brief
4. Construct and test a full-scale prototype of a selected design
5. Use feedback from testing to suggest improvements to the design





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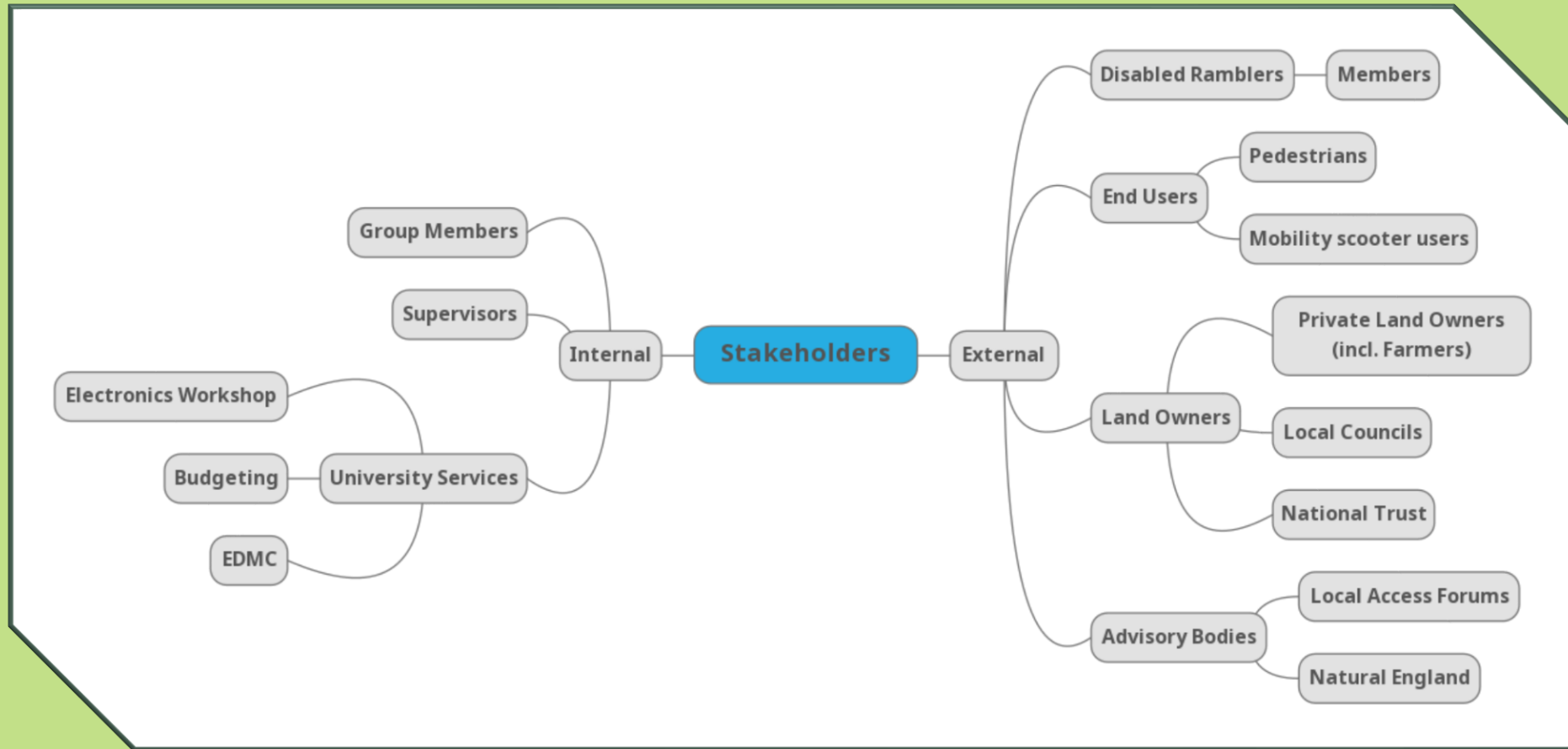
Project Review



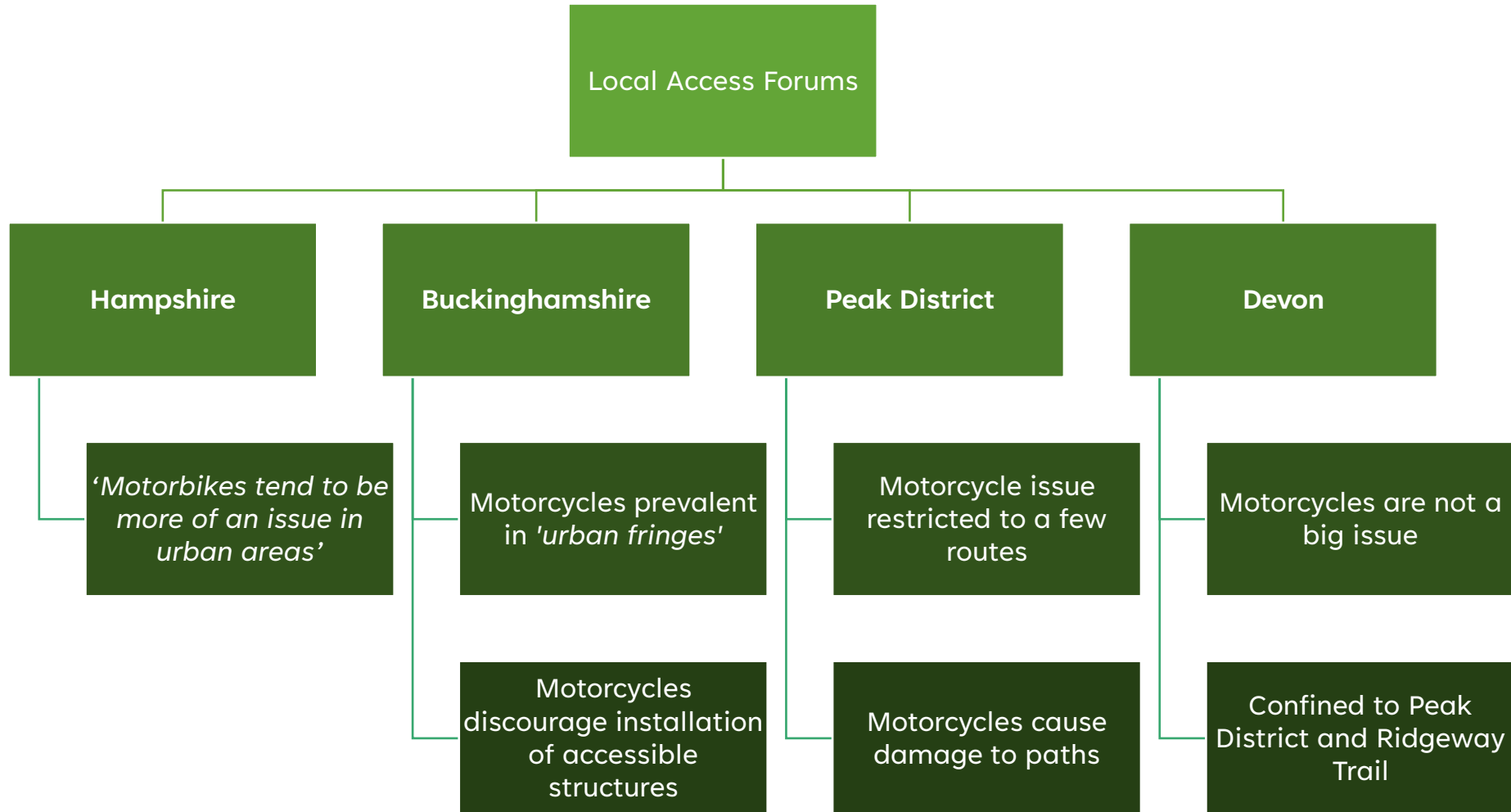
# **Background Research**



# Identification of Stakeholders



# Scope of the Motorcycle Issue







# Legal Aspects

## Equality Act 2010:

- Requirement for adjustments to be made where a *‘physical feature puts a disabled person at a substantial disadvantage’*

## Highways Act 1980:

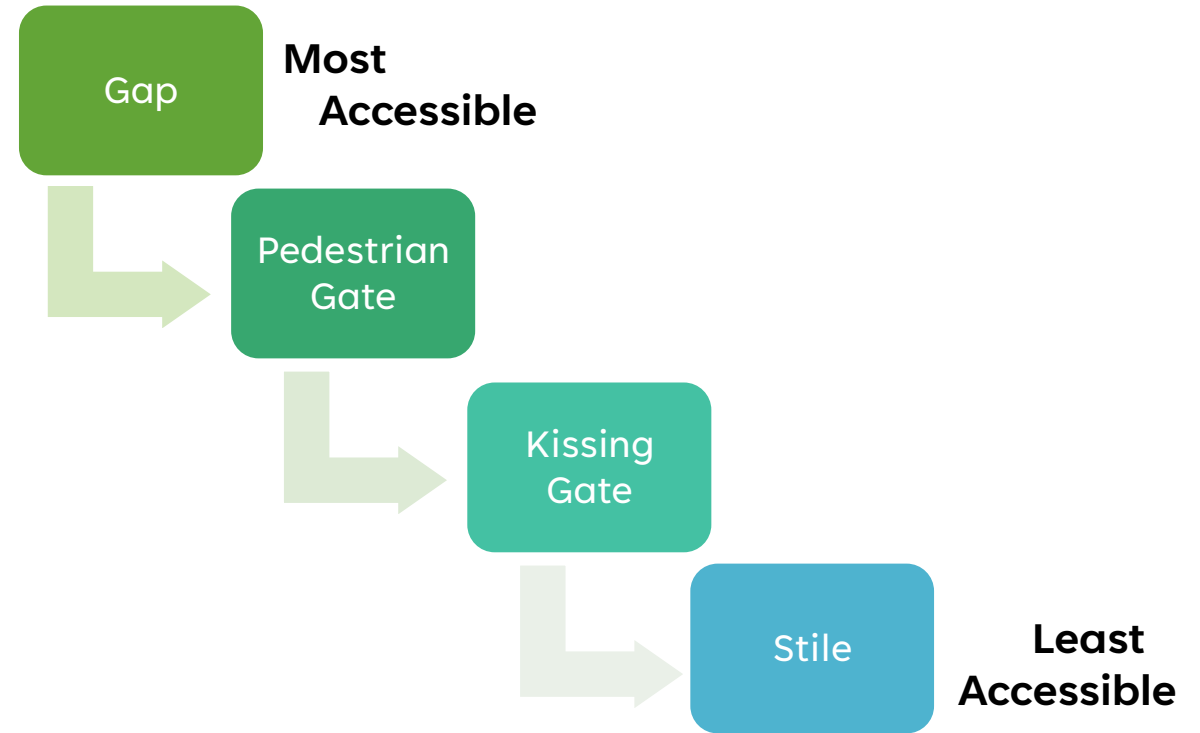
- Permission to erect a structure on a PRoW can only be granted for **stock proofing**



# Current Advice

## BS5709:2018

- Provides **guidance** on **best practice** for gaps, gates and stiles
- Advisory panels use BS5709:2018 to **inform** their **recommendations**
- **Compliance** means a structure is **more likely** to be **recommended**



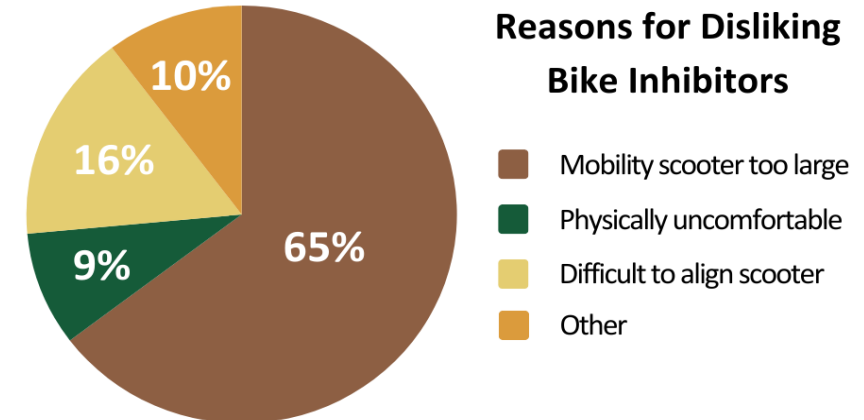
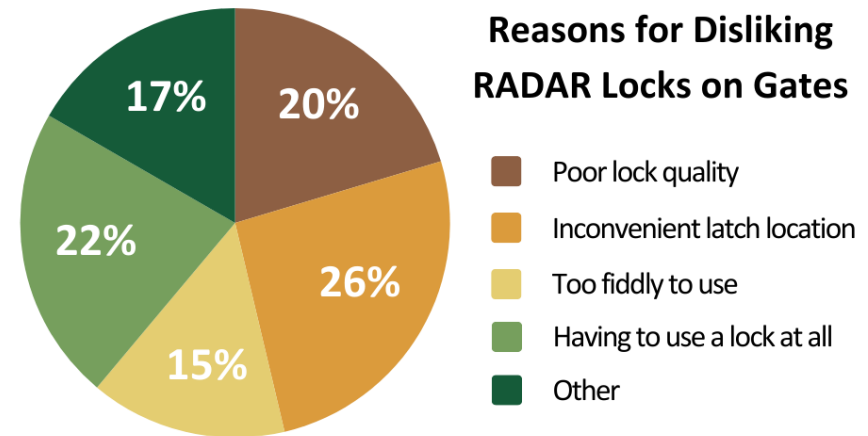
# User Opinions on Existing Structures

**91% HAVE BEEN DETERRED FROM A TRIP BY THE THOUGHT OF USING A GATE**

**70% IDENTIFIED PUSHING AWAY AS THE EASIEST MOTION FROM A MOBILITY SCOOTER**

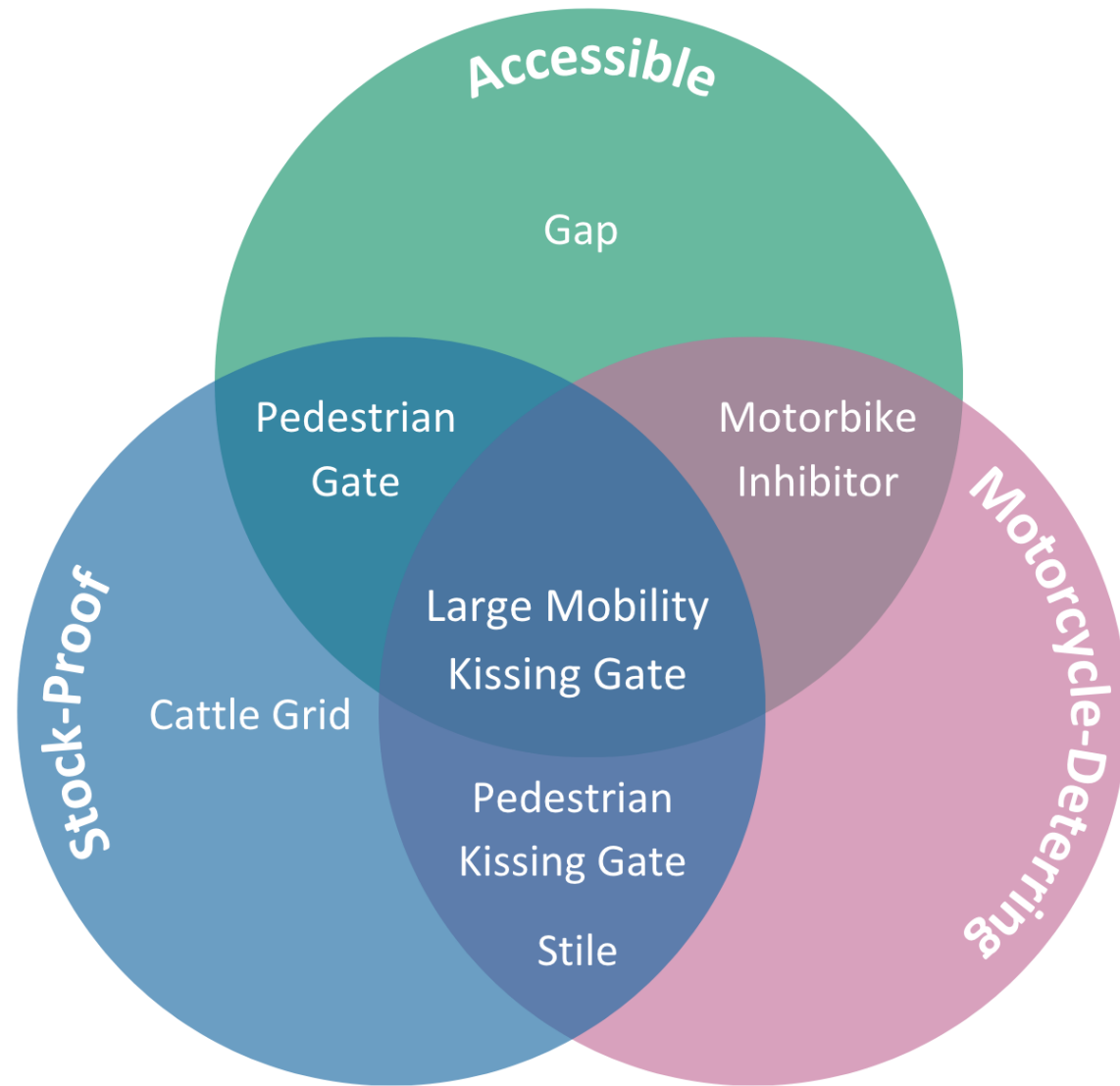
**80% RATED THEIR EXPERIENCE WITH BIKE INHIBITORS AS NEGATIVE**

**33% RATED THEIR EXPERIENCE WITH RADAR LOCKS ON GATES AS NEGATIVE**



# Existing Gates & Structures

- Reflects the **intention** of each solution
- **Effectiveness** is often subjective



# Existing Gates & Structures: Motorcycle Deterrents



## Stiles

- + Steps allow pedestrian access
- Mobility scooter access not possible



## Large Mobility Kissing Gate

- + Hoop section prevents motorcycle access
- + RADAR key padlock allows mobility scooter access
- Position of padlock is awkward



## Bike Inhibitor

- + Fixed width -> catches handlebars of motorcycles
- Limited clearance



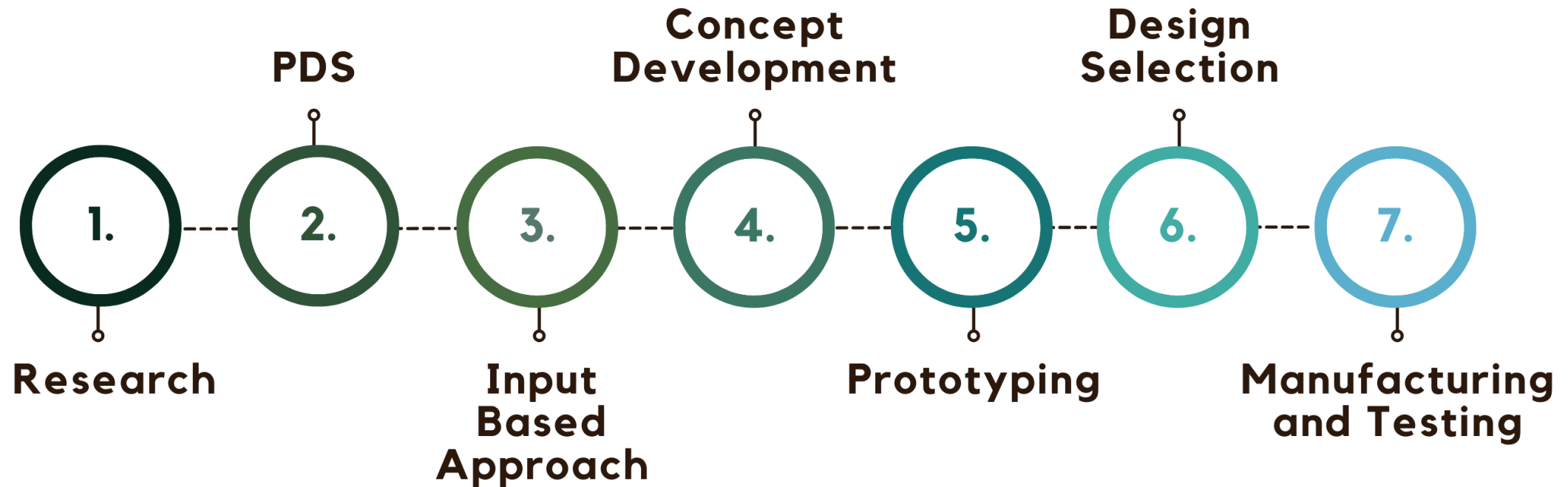
# Summary of Findings

- **Keys** are **difficult** to use
- Bike inhibitors prevent large scooters
- **Hands-free** operation preferable
- In rural areas, **motorcycles** are a **perceived issue**
- **Motorcycle** issues are **localised** & confined to 'urban fringes'
- **Larger landowners** (National Trust) may be willing to **pay more**
- **Maintenance** of current gates is **infrequent**

# Design Process



# Design Process Overview





# Product Design Specification

Design Specification Category	Specification Target
Aesthetic	<ul style="list-style-type: none"><li>• Compliments surroundings</li></ul>
Cost	<ul style="list-style-type: none"><li>• Manufacturing cost &lt; <b>£700</b></li></ul>
Customer	<ul style="list-style-type: none"><li>• <b>Accessible</b> from scooter seat</li><li>• <b>Operation clear</b> to the user</li></ul>
Environment	<ul style="list-style-type: none"><li>• Fully <b>reusable</b> or <b>recyclable</b></li></ul>
Safety	<ul style="list-style-type: none"><li>• Protruding <b>edges rounded</b></li><li>• Few pinch points</li></ul>
Size	<ul style="list-style-type: none"><li>• Minimum <b>clearance 1.1m</b></li></ul>
Function	<ul style="list-style-type: none"><li>• Mobility scooter ✓</li><li>• Pedestrians ✓</li><li>• Motorcycles ✗</li></ul>
Materials and Manufacturing	<ul style="list-style-type: none"><li>• Standard material sizes</li><li>• <b>Weatherproof</b></li></ul>

# Input-Based Approach

Weight Input



2-Wheel Axle Input



2D/3D Profiles



Physical Driver Inputs



Electronic Input



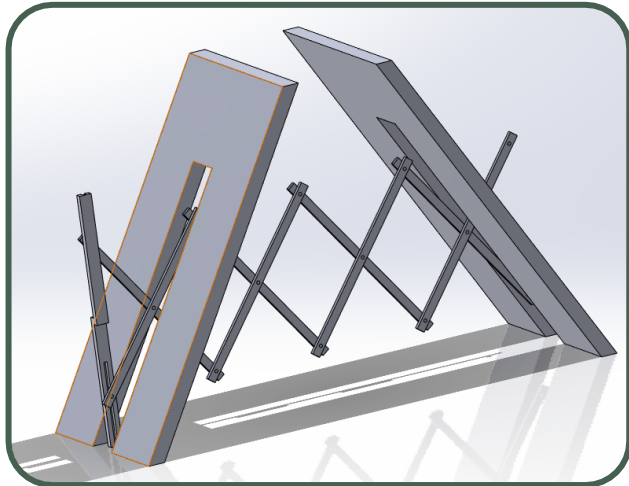
Electronic Input from Scooter



Thrust from Scooter

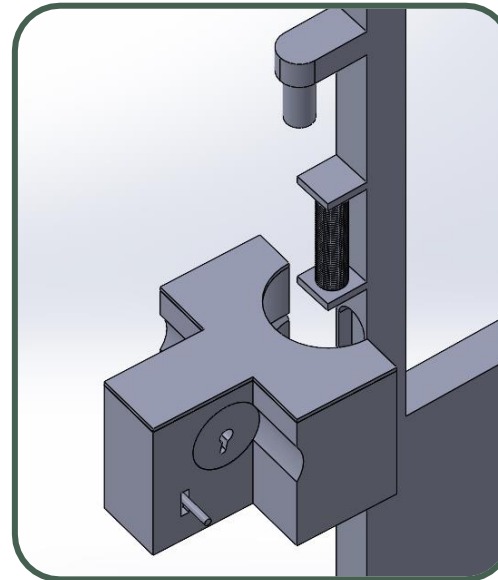


# Design Concepts



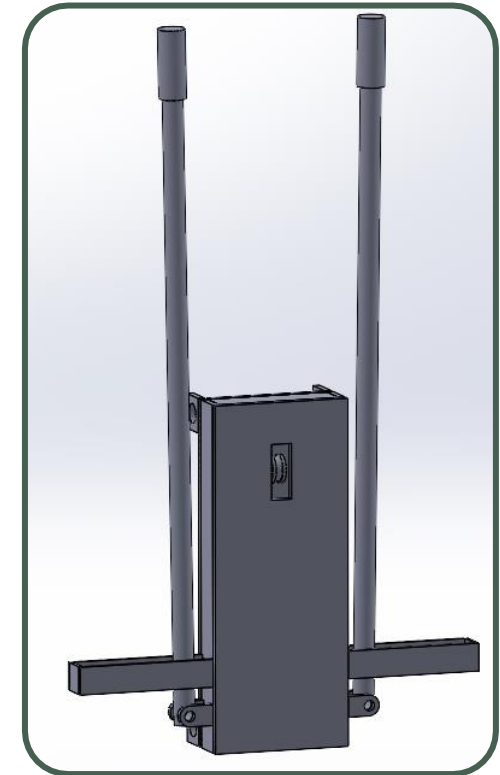
## A-Frame

- Reassessment of existing frame dimensions
- Considered mobile and static versions



## RADAR Kissing Gate

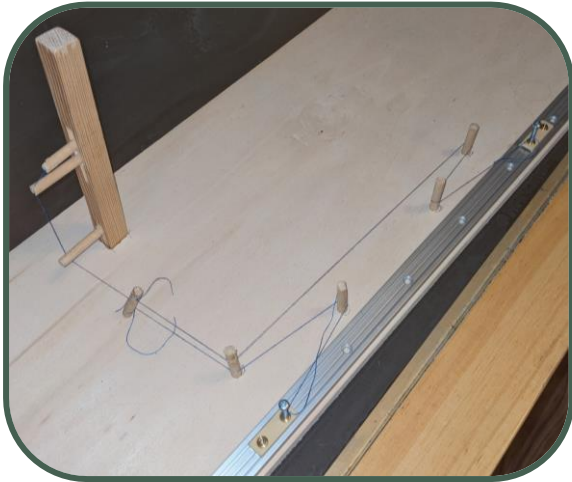
- Positional improvements
- One-handed operation



## Lever Operated

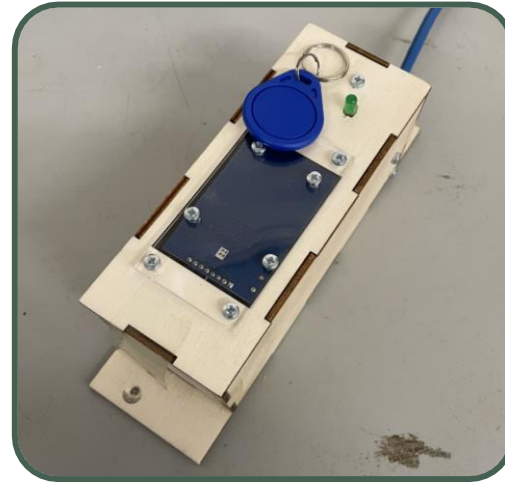
- Easy to operate
- Can incorporate RFID + RADAR key

# Design Concepts



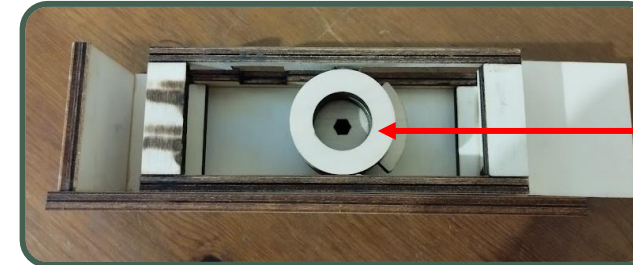
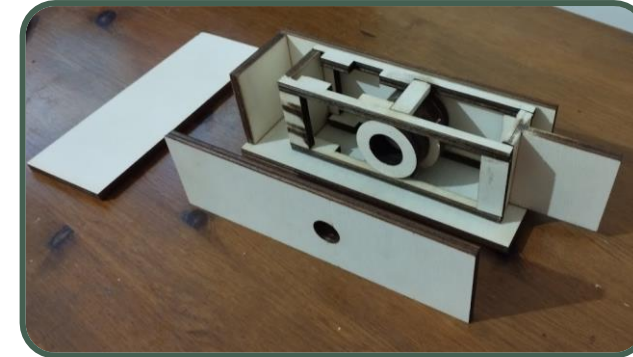
## Ride-On Mechanism

- Exploits 2 parallel wheels on one axle
- Completely hands-free



## RFID Kissing Gate

- Easy-tap fob
- Stock electronic components



Insert chosen  
key profile here

## Pole Key

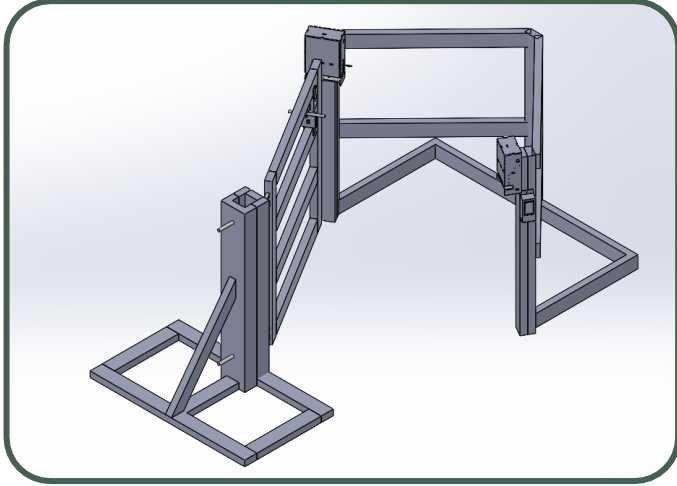
- Custom key profile fitted to a mobility aid
- Well-developed existing mechanism

# Design Matrix

Category	Weighting (1-5)	Reasoning
Aesthetic	1	Easier to market
Cost Efficiency	2	Competitive pricing
Manufacturing and Material Efficiency	3	Reduce production costs and environmental impact
Maintenance	4	Ensure longevity and functionality of structure
Ease for Mobility Scooters	5	Design Project Aim
Prevention of Motorcycles	5	Design Project Aim
Ease to Make Two-Way	4	Easier for those in wheeled mobility aids
Self-Closing	5	Vulnerable to livestock/those with unauthorised access
Access for Pedestrians	3	Desirable to install on public footpaths
Spatial Requirements	2	Smaller ground footprint

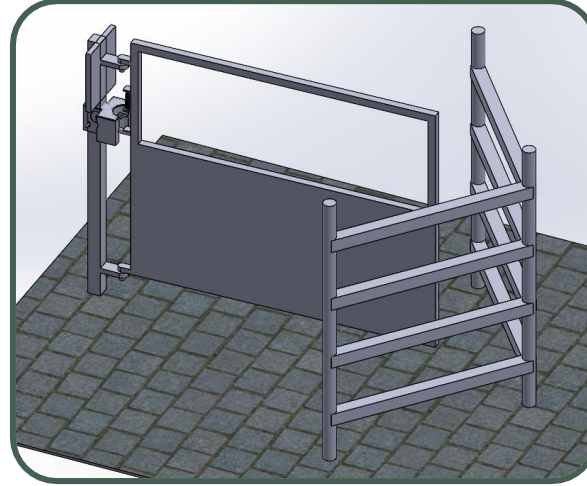
**The benchmark Aston 2-way gate produced a score of 113**

# Design Selection



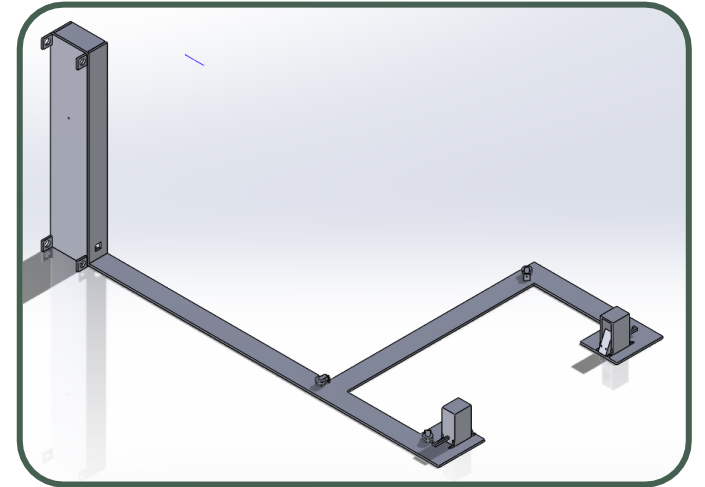
## RFID Kissing Gate

- Matrix Score of **120**
- Electronic concept
- Uses RFID to unlock the mechanism
- Permits standard foot traffic



## RADAR Kissing Gate

- Matrix Score of **119**
- Fully mechanical concept
- Must be reset by user
- Permits standard foot traffic

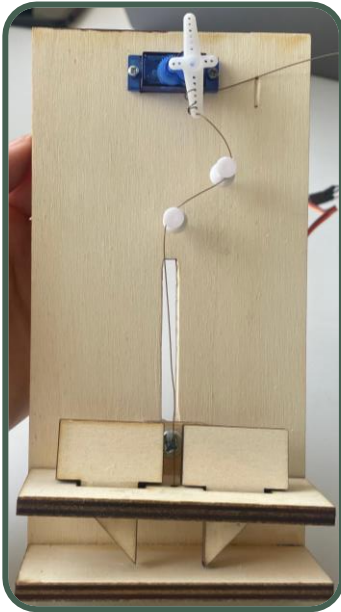


## Ride-On Mechanism

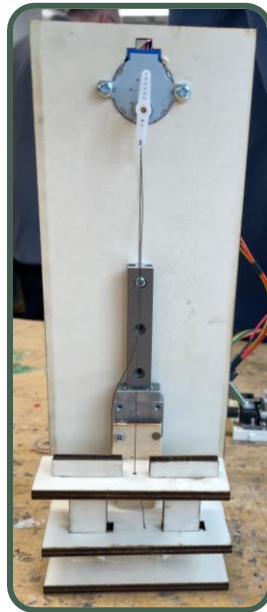
- Matrix Score of **114**
- Fully mechanical concept
- Standard self-closing method
- Hands-free operation



# Prototyping: RFID Pawls + Housing



- Floating pawls
- Pulley system



- Addition of linear rail



- Creation of the pawl housing
- Limit switches
- L-shaped crank



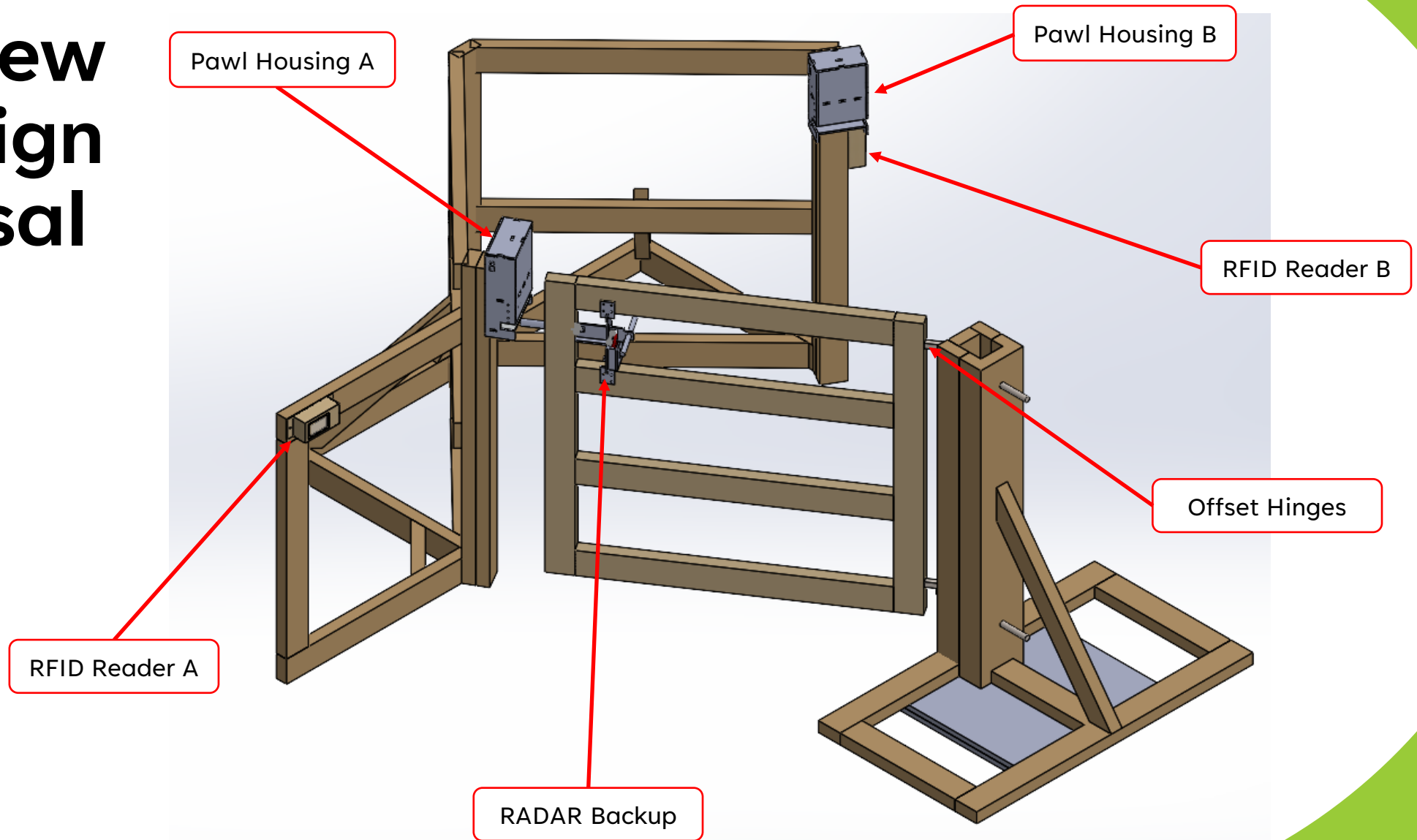
- Two linear rails
- Hinged pawls
- Connecting rod

# **Final Design Proposal**

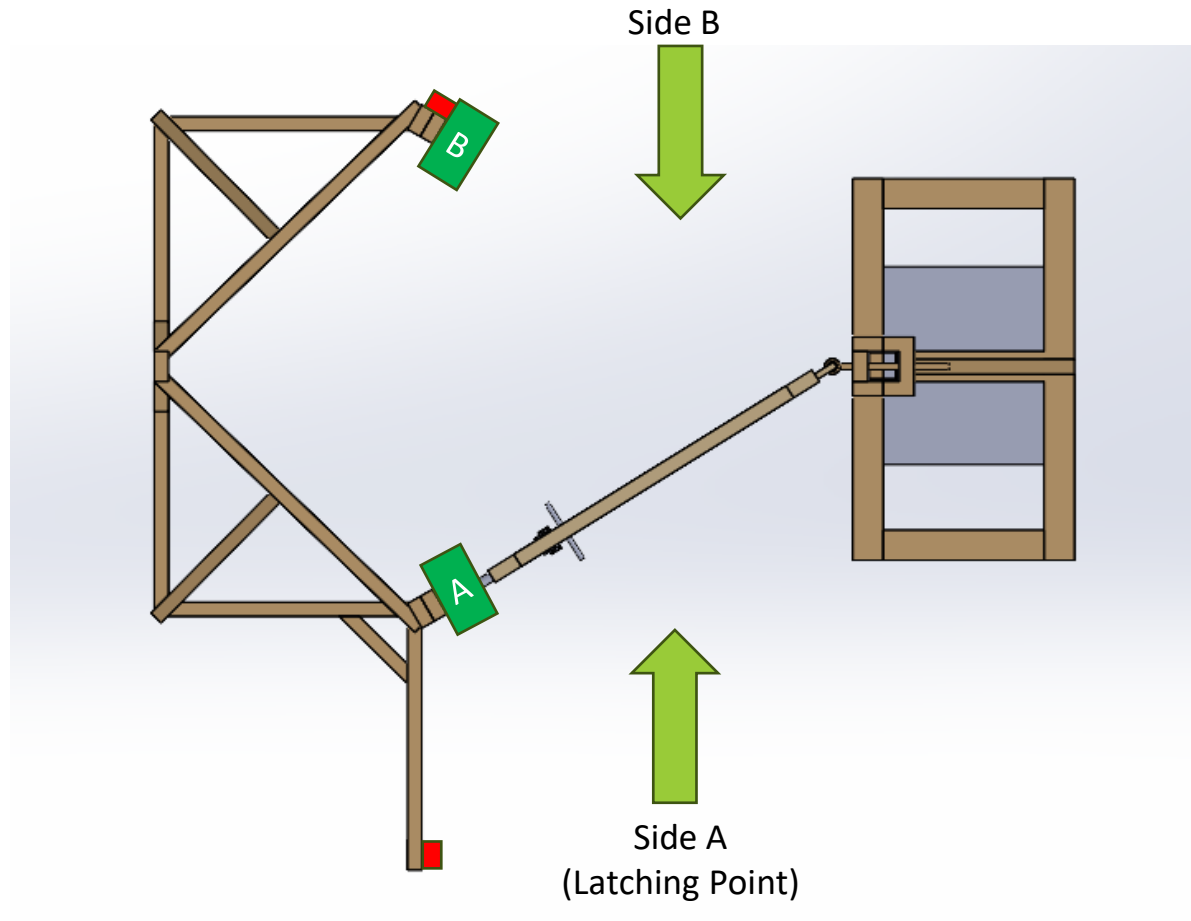




# Overview of Design Proposal



# Plan View

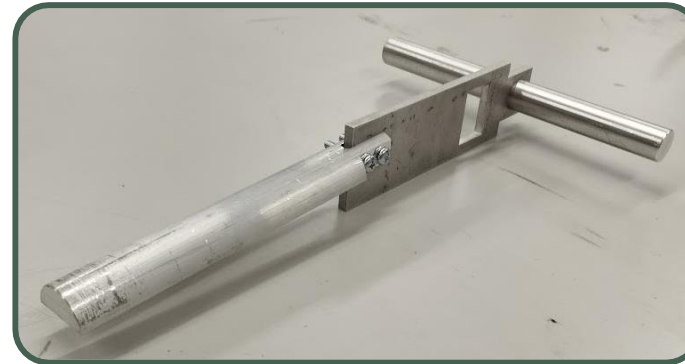
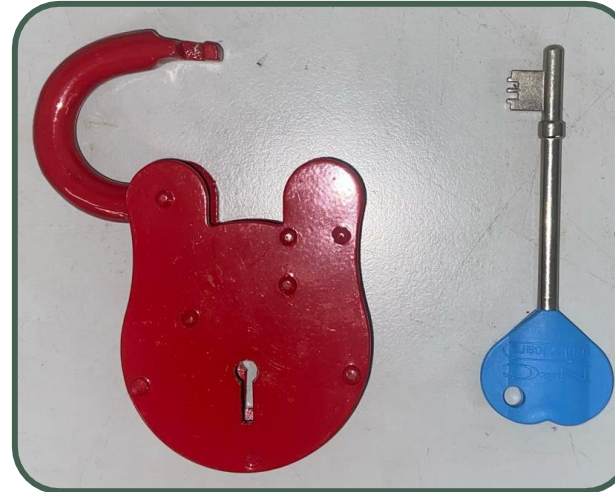


 Pawl Housing

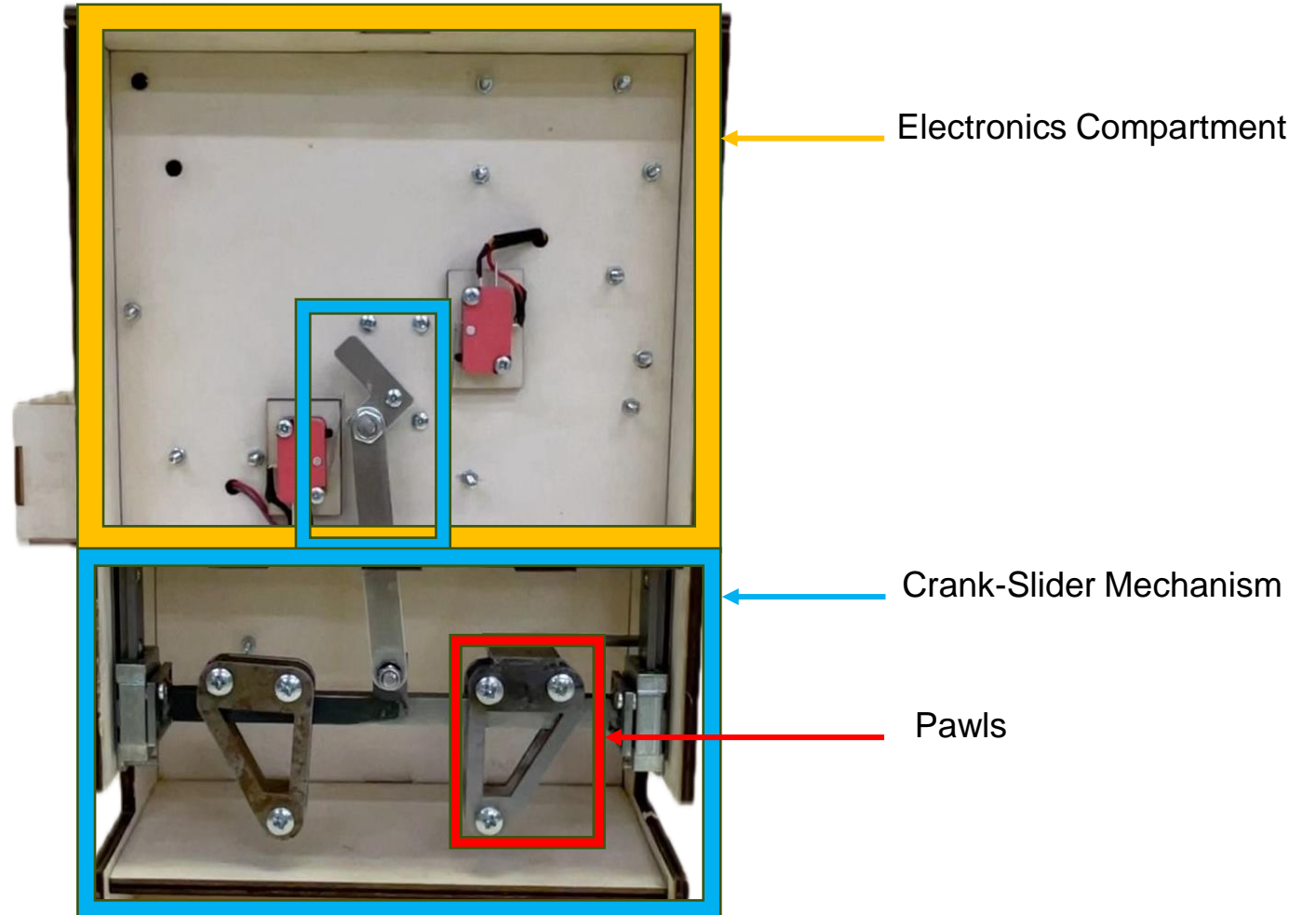
 RFID Reader

# Latch Strike Mechanism

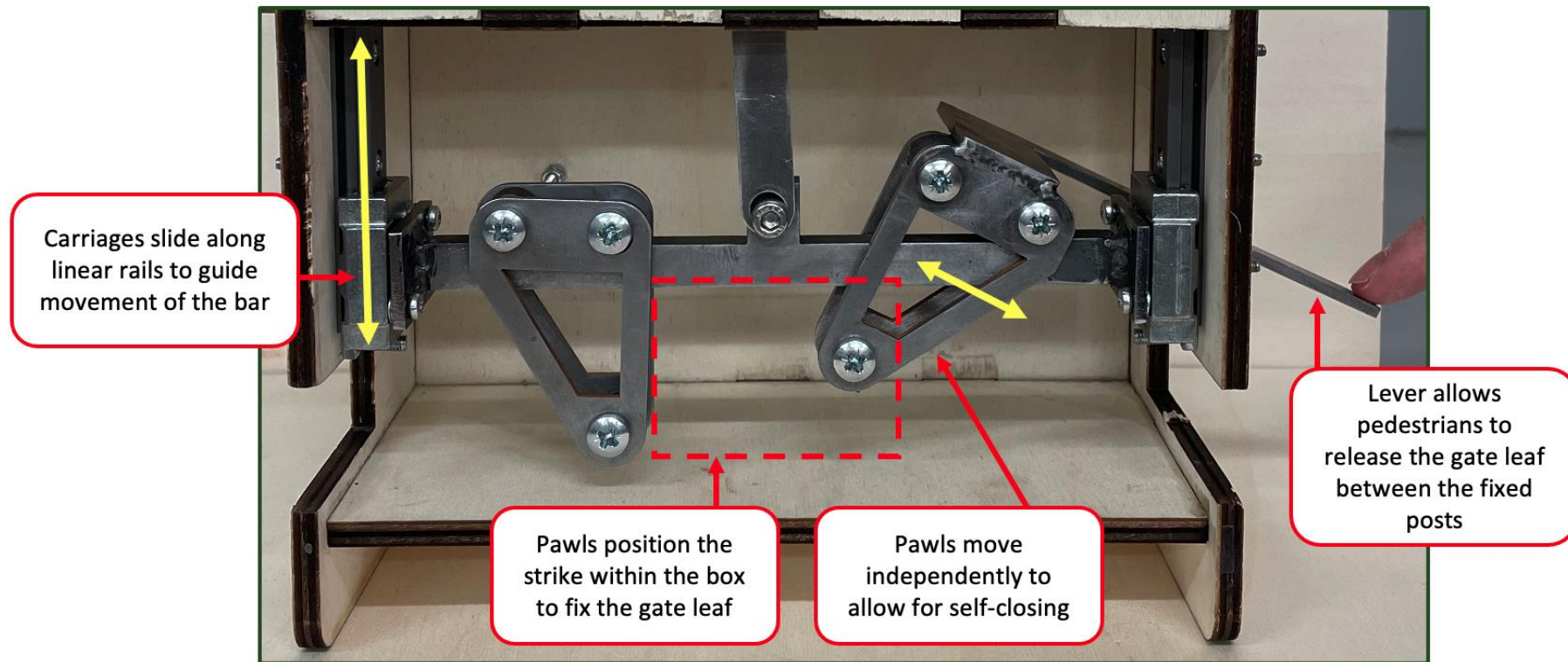
- Reproduced both a RADAR lock bracket and strike
- **Semi-circular strike profile**
- Bracket design to fit 45x95mm wood profiles
- Lightweight **aluminium**



# Crank-Slider Mechanism



# Moving Pawl Mechanism



# Electronic Functionality

Requirements:

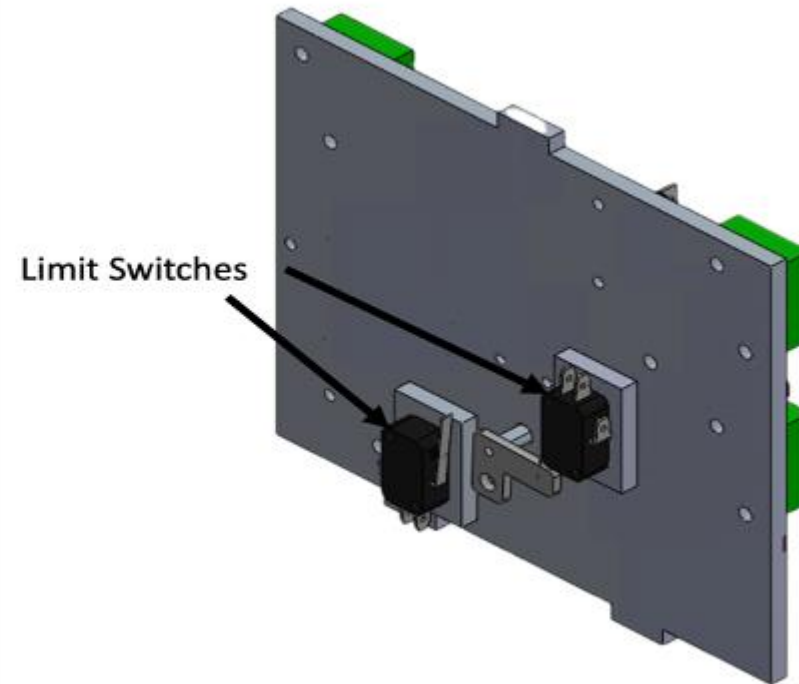
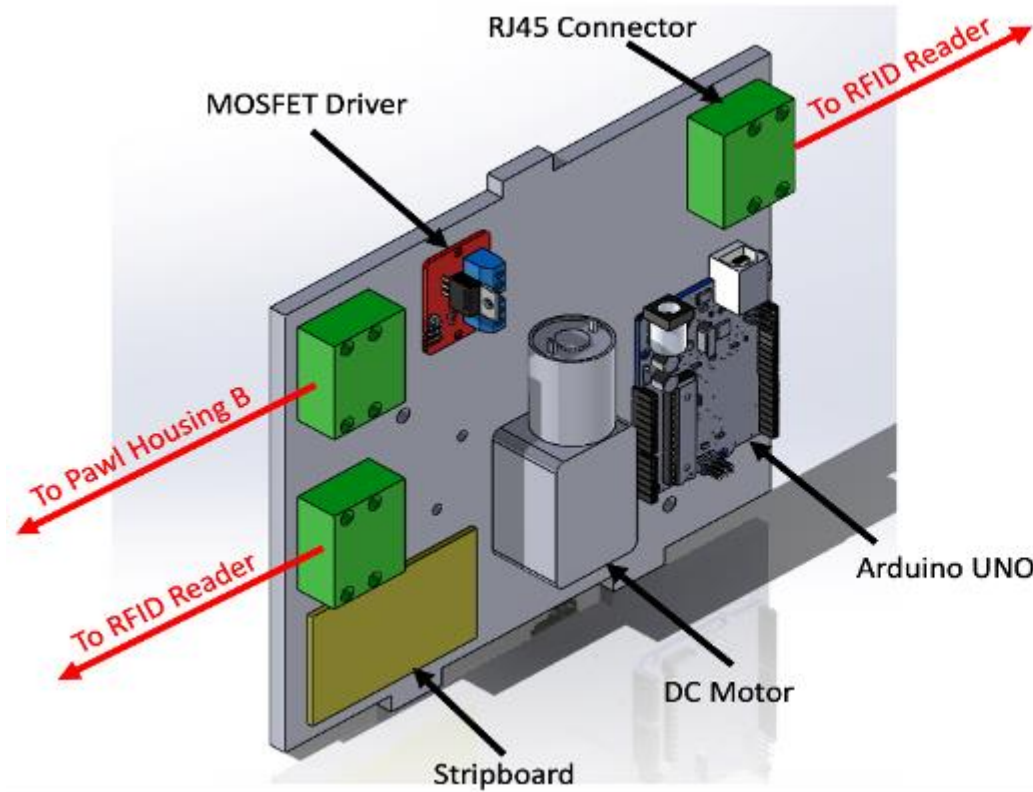
- Read RFID fobs
- Raise sliders
- Hold gate in open position
- Return to closed position

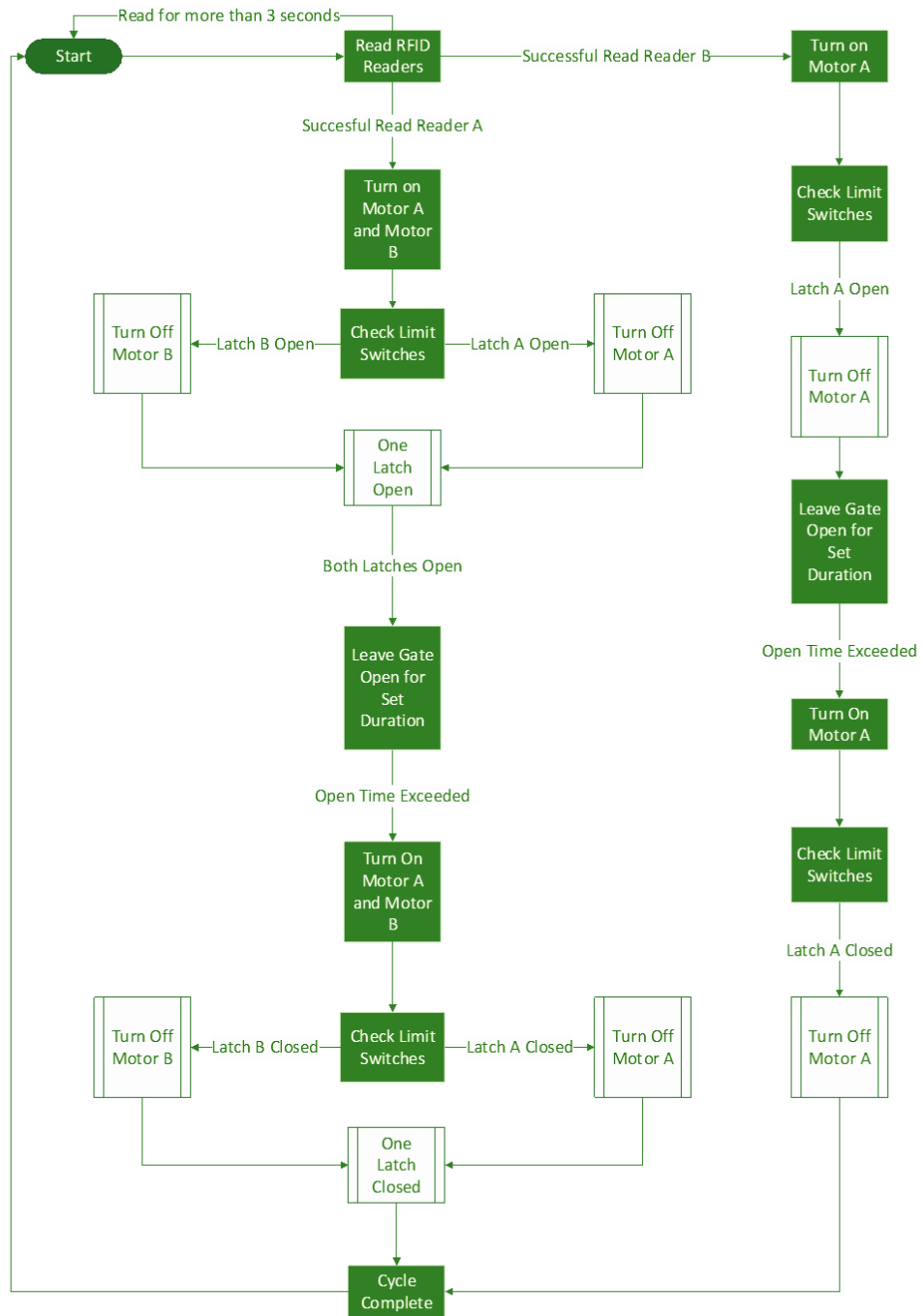


Components	Functions
Arduino UNO	<ul style="list-style-type: none"><li>• Determine state of circuit</li><li>• Control components</li><li>• Store master ID</li></ul>
RFID Readers	<ul style="list-style-type: none"><li>• Read RFID fobs</li></ul>
Limit Switches	<ul style="list-style-type: none"><li>• Determine slider position</li></ul>
DC Motors	<ul style="list-style-type: none"><li>• Raise/lower sliders</li></ul>
MOSFET Drivers	<ul style="list-style-type: none"><li>• Control power supply to motors</li></ul>
Ethernet Cables	<ul style="list-style-type: none"><li>• Transmit signals between components</li></ul>



# Component Layout





# State Machine Flowchart



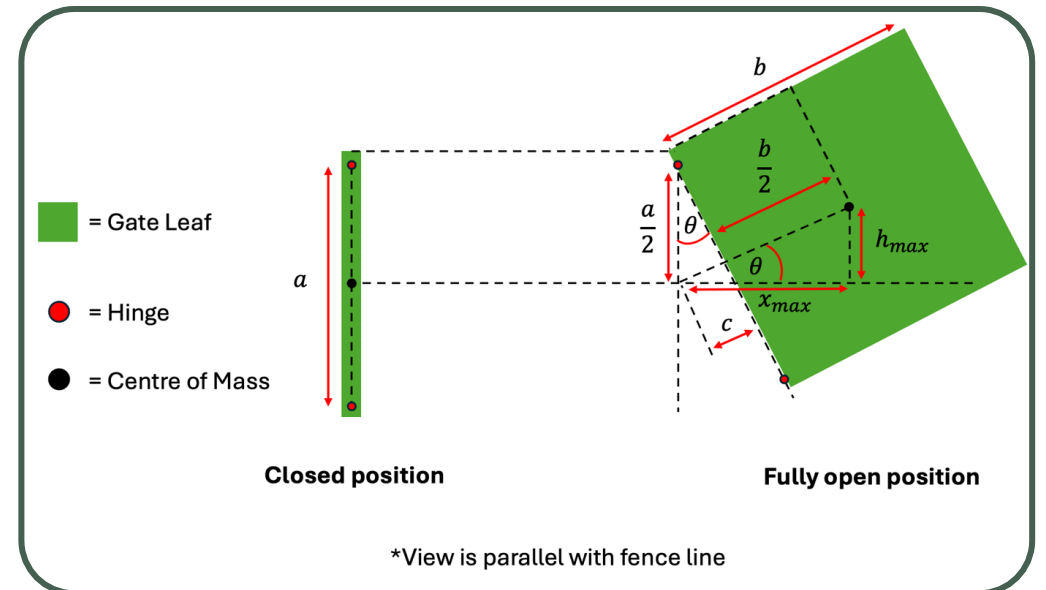


# Gate Hinges

- Required a **self-closing hinge** with **180° opening span**
- Raised mass returns gate to resting position
- **Adjustment** of resting position **unsuccessful**

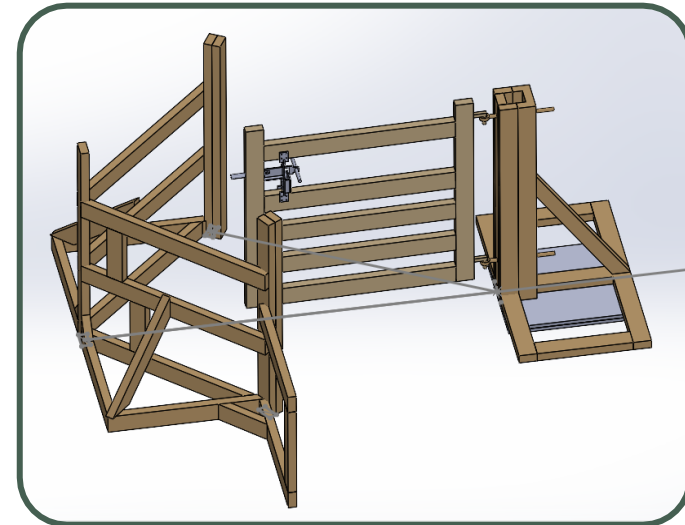
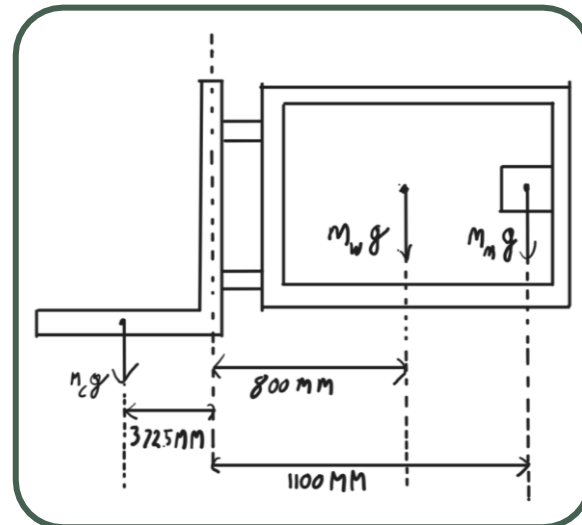
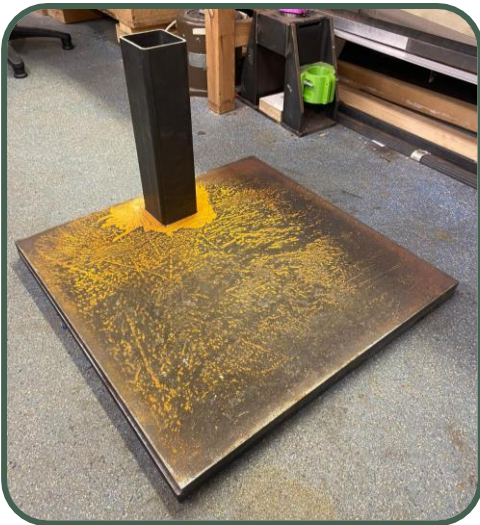


\*Image taken from Centrewire 180° hinge installation instructions



# Free-Standing Structure

- Avoided obtrusions into the gate path
- **Calculated** required **balancing forces**
- Emulated strength of a sunk gate post



# Testing Session Overview



Construction of free-standing,  
full-scale prototype



Tamper  
Testing



Strike Latching  
Functionality



# Testing Session Overview

Ergonomic features tested



RFID Functionality



RADAR Padlock



Pedestrian  
Testing



# Findings From Testing

What We Tested	What We Learned
Positioning of the RFID readers	Database-informed position was suitable
Positioning of the pawl housings	Pawl housing can be difficult to align with moving strike
Opening duration for the gate	Optimal open time for the gate was around 10 seconds
Resting position of the gate	Offset hinges provide inadequate adjustment of resting position
Effectiveness of latching mechanism	Pawls too short
Effectiveness of tamper-proofing measures	Flanged pieces and thin strike are not preventative



# Final Refinements

Slanted roof  
aids run off

Roof fixed with  
screws upholds  
maintenance

Maintenance  
hatch model

Increased  
slot size

Increased pawl  
length

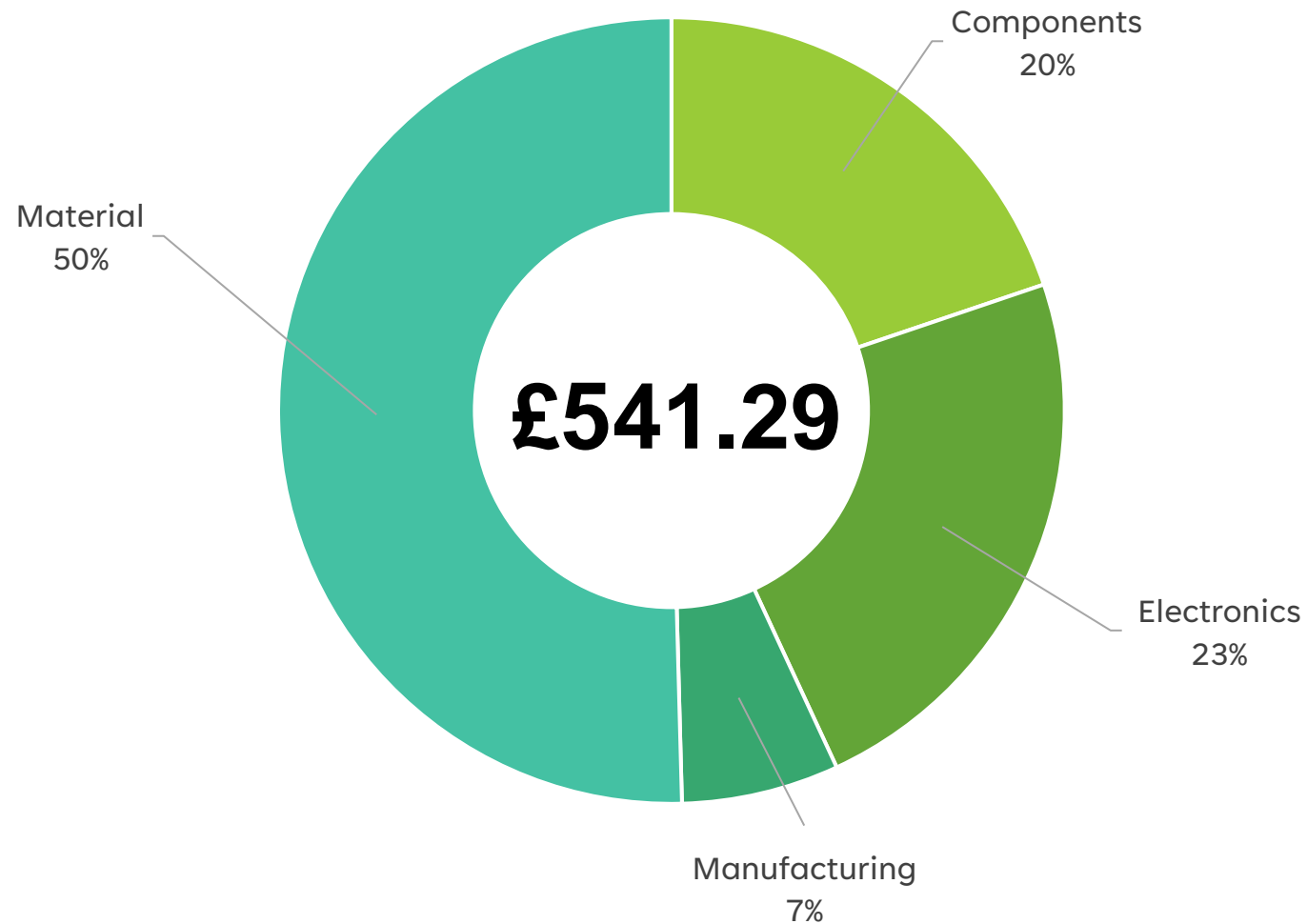


# Project Review

**Aim:** Design and manufacture a prototype structure that is both motorcycle-detering and more accessible for mobility scooter users than current designs on the market

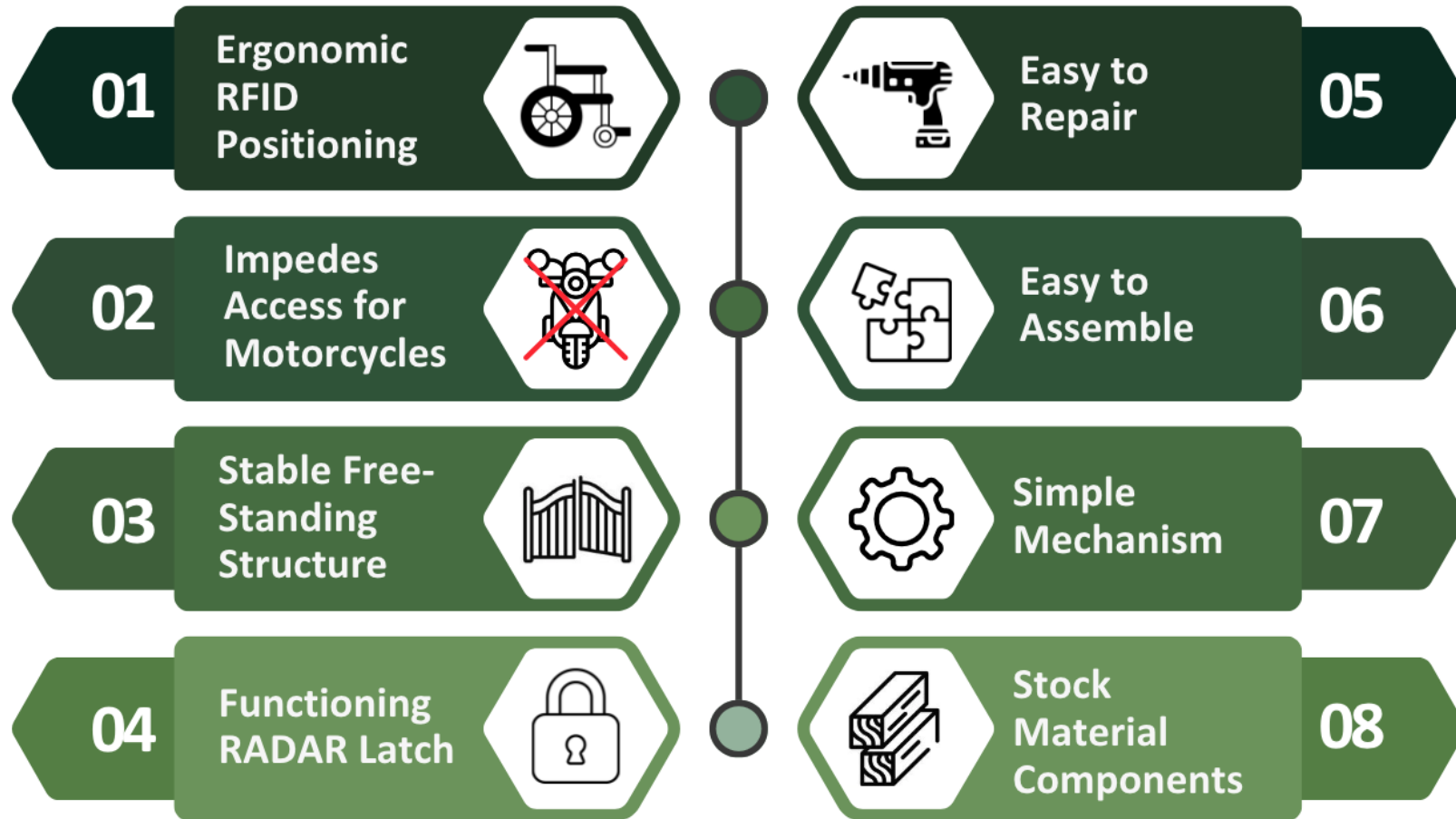


# Cost of Prototype

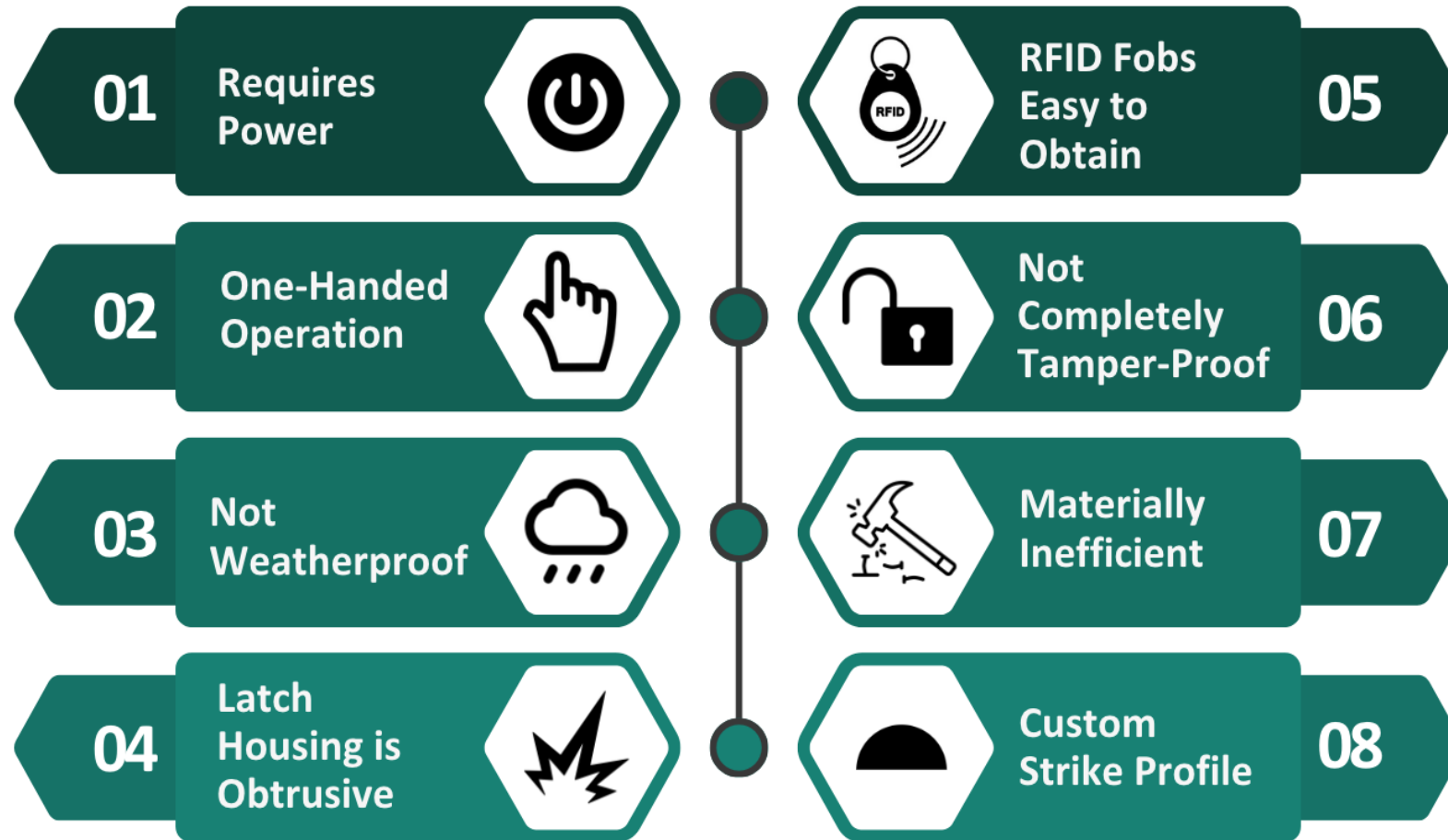




# Strengths



# Limitations



# Project Review

## Objectives:

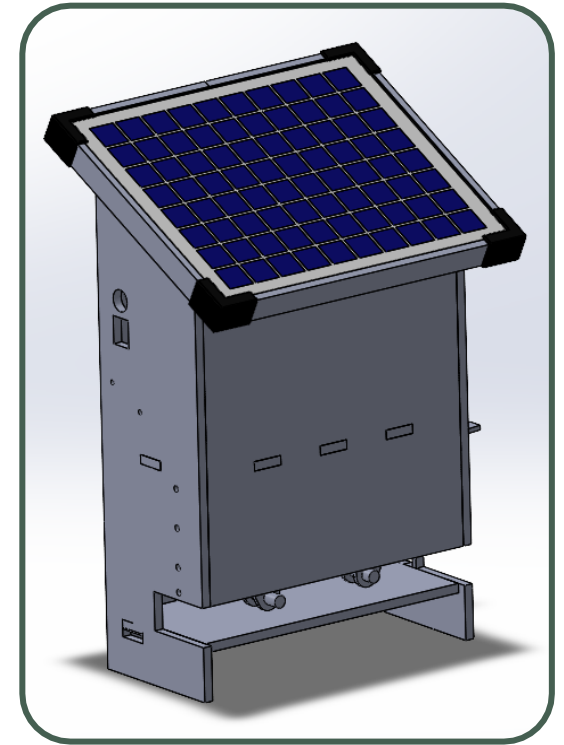
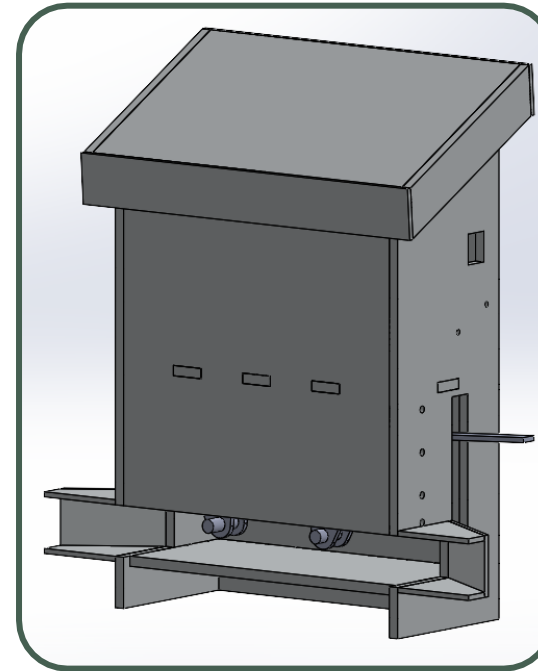
1. Investigate existing designs and viewpoints of relevant stakeholders  
Motorcycle-detering structures are not ergonomic for mobility scooter users.
2. Use product design specification to identify areas for improvement.  
PDS highlighted improvements could be made in positioning of unlatching mechanism.
3. Produce multiple design solutions that resolve the design brief.  
An RFID-based kissing gate was selected for prototyping.
4. Construct and test a full-scale prototype of a selected design.  
A free-standing gate was constructed and tested with a mobility scooter.
5. Use feedback from testing to suggest improvements to design.  
Further design iteration produced after testing.

# **Future Work**



# Future Improvements

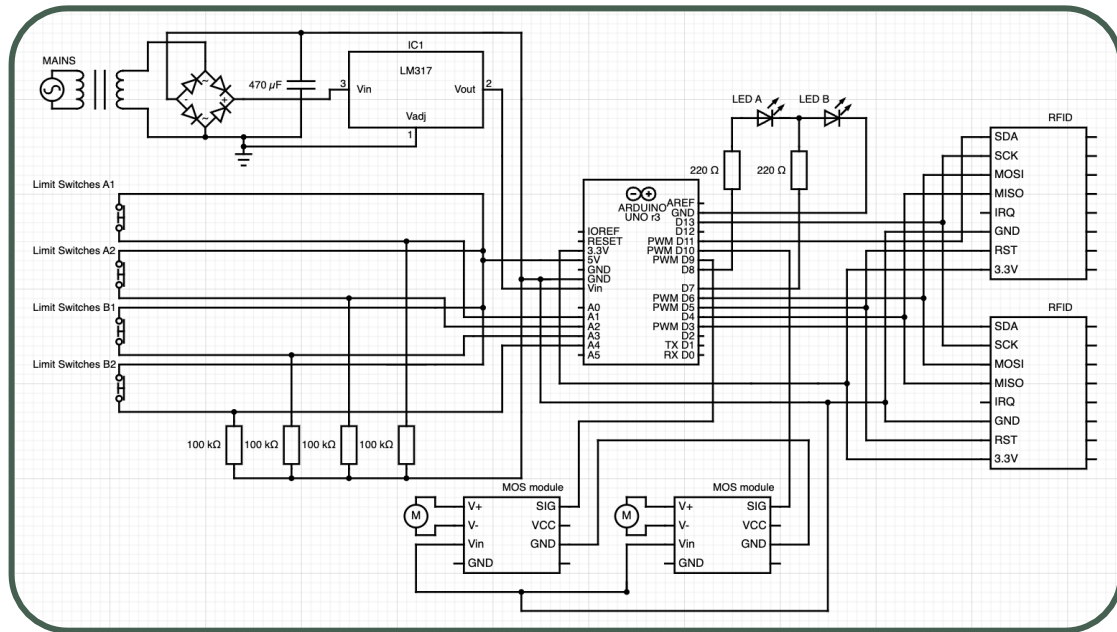
- Steel or aluminium welded casing
- Reassess required material thickness
- Add flanges to strike channel
- Reconfigure pawl housing mounting
- Improved components
- PV power source



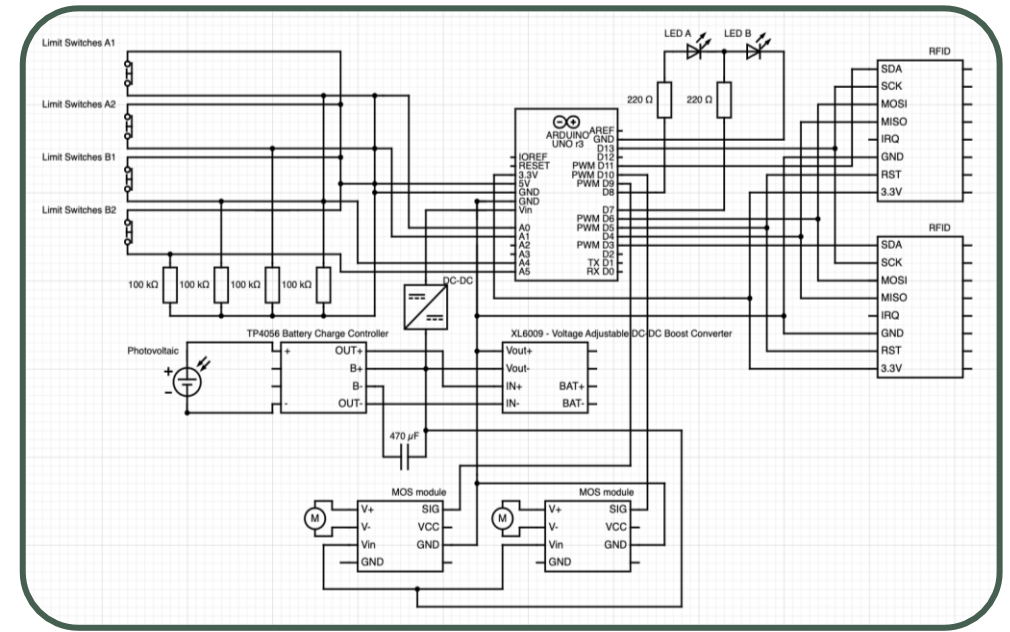
# Power Solutions

Average energy consumption of 1.25Wh per day assuming 80 daily uses

- Solar solutions able to provide approx. 10 times power required
- Additional power charges backup battery



Mains Power Source



Photovoltaic Power Source

# Thank you to...

- Participants & Volunteers
- Prof. Anna Barney
- Prof. David Richards
- Shail Patel
- Dr. Matthew Wright
- The Disabled Ramblers Charity
- The Centre for  
Outdoor Accessibility Training
- Val Woods
- Tom Bindoff
- Centrewire
- The Disabled Ramblers'  
community



# Questions

Thank you for listening

